

Simple method to reduce the eccentricity of Binary Black Hole simulations with the EinsteinToolkit

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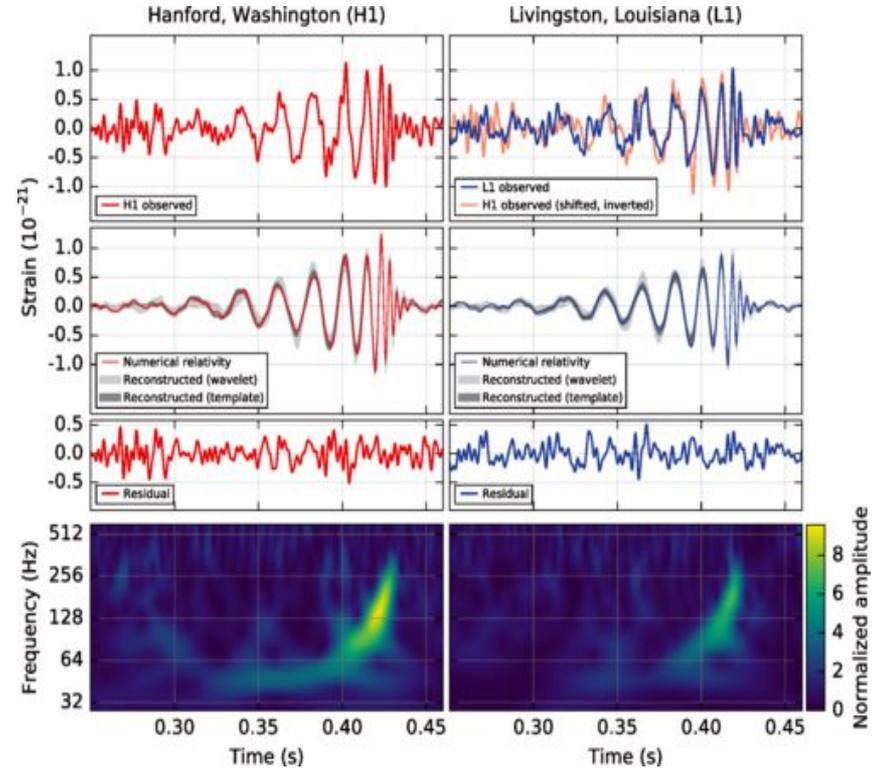
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Introduction. Gravitational wave motivation

- Current GW observations from BBHs coalescences are compatible with low eccentricity systems.
- Most of the binary systems are expected to have circularized by the time their GW signals enter the frequency band of the LIGO and Virgo detectors.



Introduction. Framework

- Eccentricity Reduction → within the phenomenological waveform modelling efforts. (Geraint's talk)
- BBH simulations are run with BAM and ET codes to get waveforms.
- Imperfections of NR initial data → waveforms with residual eccentricity.
- **Main Objective:** Establish a systematic procedure to reduce eccentricity.

Initial data for NR simulations of BBH

- 1) Choose r and \vec{S}_1, \vec{S}_2 .
- 2) Choose \vec{p}/\vec{v} of the BH such to result in low eccentricity. (PN approximations)
- 3) Solve numerically the constraints equations. (usually conformal flatness)
- 4) Evolve data numerically until eccentricity can be measured reliably from oscillations in $r, \phi, \omega, \phi_{22}, \omega_{22}, \dots$
- 5) A correction to the initial parameters is applied, and steps 2-5 (or 1-5) are applied until eccentricity is low enough for applications.

Introduction. Eccentricity estimators

- In numerical simulations, small eccentricity \rightarrow small residual oscillations with amplitude proportional to the eccentricity are added monotonically changing orbital variables.
- In GR no unique definition of the eccentricity!
- Quantities such as the orbital frequency get eccentricity as

$$\Omega(t) = D(t) + e_{\Omega}(t) \cos(\Omega_r t) \quad (1)$$

- We define an eccentricity estimator of the form

$$e_{\Omega} = \frac{\Omega(t) - \Omega_{fit}(t)}{2\Omega_{fit}(t)} \quad (2)$$

Election based on the nearly gauge-independence of the orbital frequency, Ω .

Introduction. Iterative methods

- Iterative schemes \rightarrow Most efficient way to reduce e_t from numerical simulations.
- Given initial config. $(r_0, p_r^0, p_t^0, \chi_1, \chi_2)$ modify $(p_r^0, p_t^0/r_0)$ to reduce the eccentricity .
- Summary:

- 1) Provide initial values for (p_r^0, p_t^0, r_0) data at a given separation/orbital freq.
- 2) Measure the eccentricity e_0 from the simulation.
- 3) Use e_0 to compute $(\lambda_r, \lambda_t/\delta_r)$.
- 4) Apply the correction factors:

$$\begin{aligned} p_r^1 &= \lambda_r^0 p_r^0 & p_r^1 &= \lambda_r^0 p_r^0, \\ p_t^1 &= \lambda_t^0 p_t^0 & r_1 &= r_0 + \delta r \end{aligned}$$

- 5) Run the a simulation with the new parameters and measure the eccentricity e_1 from the new simulation.
- 6) If the eccentricity is not low enough go to step 3).

Eccentricity measurement (I)

- A fit to the data (NR or PN) is necessary to compute $e_\Omega(t)$. (*Mathematica NonlinearModelFit function*)

- We use an Ansatz based on the TaylorT3 approximant [Buonanno et al. Phys.Rev.D80,084043(2009)]

$$\theta = [\eta|T_{merg}t_0 - t|/5]^{-1/8}$$
$$A = \frac{a_1\theta^3}{16\pi} (1 + b_2\theta^2 + b_3\theta^3 + b_4\theta^4 + b_5\theta^5 + b_6\theta^6)$$
$$ansatz = A + a_6 \cos(\Omega_0\omega_1 t + t_1)$$

- T_{merg} is an scale of the merger time.
- $b_2, b_3, b_4, b_5, b_6 \rightarrow$ analytical coefficients from TaylorT3.
- $t_0, a_1, a_6, \omega_1, t_1$ are unknown coefficients to fit.
- Ω_0 is the 3.5PN orbital frequency for quasi-circular orbits.

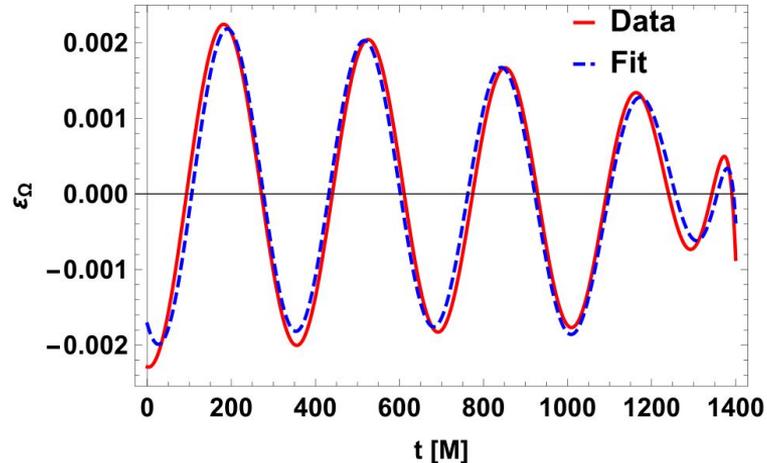
Eccentricity measurement (II)

- The ansatz can be identified with the residual between the data and our model based on 3.5PN approximant.

$$\mathcal{R}(t) = \Omega(t) - \Omega_0$$

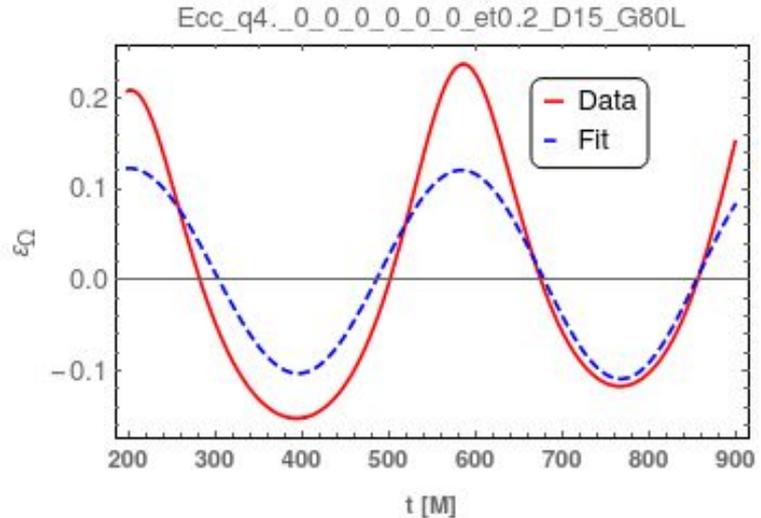
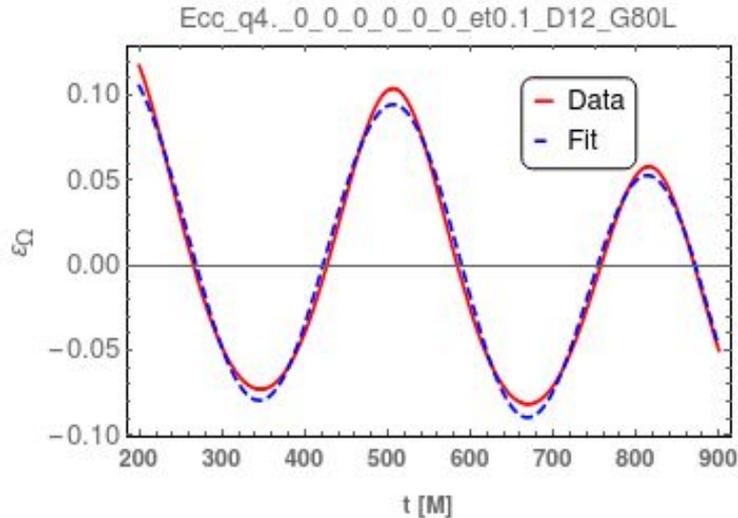
- Once the model is fitted to data, e_Ω can be calculated from the amplitude of the oscillations,

$$e_\Omega = \frac{1}{2} \frac{a_6}{\Omega_0}, \quad \delta e_\Omega = \frac{1}{2} \frac{\delta a_6}{\Omega_0}.$$



Limit eccentricity measurement

- Eccentricity measurement tested to work up to $e \sim 0.1$
- For higher eccentricities ansatz must be a sum of harmonics.



PN Initial data. Introduction

First step: Provide low eccentric initial values for (r_0, p_r^0, p_t^0) .

- Use PN theory (slow motion, weak field regime) to derive analytical formulas for $p_r(r, \eta, \chi_1, \chi_2)$ and $p_t(r, \eta, \chi_1, \chi_2)$. $\eta = m_1 m_2 / (m_1 + m_2)^2$
- From PN Hamiltonians in ADMTT gauge up to 3.5PN, we compute analytical expressions for Ω, p_r, p_t .

$$H = H_{orb} + H_{SO} + H_{SS} + H_{SSS},$$

$$p_r = 0, \quad \left(\frac{\partial H}{\partial r} \right)_{p_r=0} = 0.$$

- Once computed $p_t(r)$, then, one can compute the orbital frequency as

$$\Omega = \left(\frac{\partial H}{\partial p_\phi} \right)_{p_r=0}.$$

- The computation of p_r requires the gravitational wave energy flux,

$$-\frac{dE_{GW}}{dt} = \frac{dM}{dt} + \frac{dH_{circ}}{dt}.$$

PN initial data. Postcircular Initial data

- Using the chain rule

$$\frac{dH_{circ}}{dt} = \left(\frac{dr}{dt}\right) \left(\frac{dH_{circ}}{dr}\right) \rightarrow \left(\frac{dr}{dt}\right) \approx \frac{-\frac{dE_{GW}}{dt}}{\left(\frac{dH_{circ}}{dr}\right)}.$$

- The procedure to obtain a postcircular (PC) expression for p_r can be summarized in the following algorithm:

1. Compute the circular expression for $p_t(r)$.
2. Use the expression for $p_t(r)$ and $p_r = 0$ to compute dH_{circ}/dr .
3. Combine dH_{circ}/dr with the GW flux for the QC orbits, dE_{GW}/dt , to obtain dr/dt .
4. Use Hamilton's equations to compute $dr/dt = \partial H / \partial p_r$. Taylor expand at first order in p_r of the RHS and isolate p_r as a function of dr/dt .
5. From step 4 compute an expression of p_r using the value of dr/dt calculated in step 3.

PN initial data. Postpostcircular Initial data

- Extensively used to construct initial data for EOB dynamics.
- It describes a prescription to compute p_t using the PC information.
- Start with the Hamilton's equation for the radial momentum

$$\frac{dp_r}{dt} = - \frac{\partial H}{\partial r}.$$

- LHS of can be approximated using the chain rule and the PC solution to

$$\frac{dp_r}{dt} = \frac{dp_r}{dr} \frac{dr}{dt} \approx \frac{dp_r^{PC}}{dr} \frac{dr}{dt} = \frac{dp_r^{PC}}{dr} \frac{\partial H}{\partial P_r}.$$

- Combining these equations we get:

$$- \left[\frac{\partial H}{\partial r} \right]_{p_r=p_r^{PC}} \approx \left(\frac{dp_r^{PC}}{dr} \right) \left[\frac{\partial H}{\partial p_r} \right]_{p_r=p_r^{PC}}.$$

- Given $p_r, r, m_1, m_2, \vec{\chi}_1, \vec{\chi}_2$; one can solve for p_t using a root finding method.

PN correction factors. Introduction (I)

- When PC and PPC initial data produce a simulation with non-negligible eccentricity \rightarrow iterative step is needed.
- Initial linear momenta corrections: $(p_t, p_r) \rightarrow (\lambda_t p_t, \lambda_r p_r)$.
- One can also choose: $(r, p_r) \rightarrow (r + \delta r, \lambda_r p_r)$.
- We provide analytical expressions to compute $\lambda_t, \lambda_r, \delta r$.
- Computations based on the Quasi-Keplerian 1PN equations of motion.

$$n_t(t - t_0) = u - e_t \sin u,$$

$$(\phi - \phi_0) = (1 + k)A_{e_\phi}(u),$$

$$A_{e_\phi}(u) = 2 \arctan \left[\left(\frac{1 + e_\phi}{1 - e_\phi} \right)^{1/2} \right],$$

$$r = a_r(1 - e_r \cos u),$$

- e_t, e_r, e_ϕ are the temporal, radial and angular eccentricities, n_t is called the mean anomaly, u is the true anomaly and k is the fractional periastron advance per orbit.

PN correction factors. Introduction (II)

- From QK eqs. at 1PN the radial coordinate, r , and the orbital frequency, $\Omega = \dot{\phi}$ up to linear order in eccentricity are:

$$r = a_r (1 - e_r \cos[\Omega_r t]),$$

$$\Omega \equiv \dot{\phi} = \Omega_\phi (1 + (e_\phi + e_t) \cos[\Omega_r t]).$$

- We define an eccentricity estimator for the orbital frequency as

$$e_\Omega = \frac{\Omega(t) - \Omega(e=0)}{2\Omega(e=0)}$$

Introducing eq. for Ω in eq. for e_Ω , one gets

$$e_\Omega = \frac{e_\phi + e_t}{2}.$$

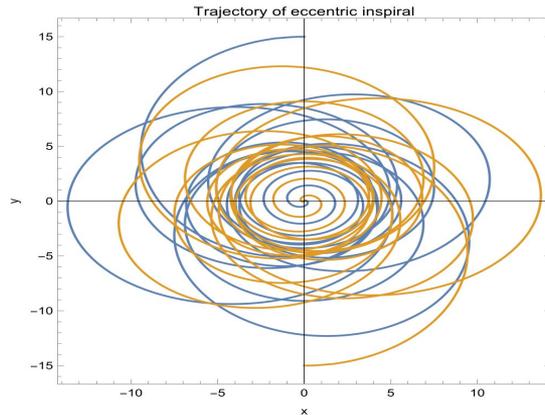
PN correction factors: 1D problem

- From the 1PN QK solution of the equations of motion one can obtain an estimate of the correction factor for p_t .

$$\lambda_t = 1 + \frac{e_\Omega}{2} - \frac{e_\Omega}{2rc^2} (\eta + 2).$$

- Details of the computation in the upcoming paper (Ramos et al 2018).
- 1D computation limiting. Not able to reduce the eccentricity over some threshold.

- This equation can be used to generate eccentric NR simulation given a desired eccentricity (at leading order).



PN correction factors: 2D problem (I)

- 2D problem (λ_t, λ_r) or $(\delta r, \lambda_r)$: follow another procedure.
- **Main goal:** fit the data using an ansatz made of **2 components**: a **non-eccentric** part + an **oscillatory** one.
- Hence, the relative oscillations in Ω can be fitted using an ansatz like

$$\mathcal{R}_\Omega = A + B \cos(\Omega_r t + \Psi),$$

where Ω_r is the frequency of the radial oscillations, and A, B, Ψ are coefficients to be determined.

- We have derived analytical expressions for $\lambda_t, \lambda_r, \delta r$ in terms of the amplitude, B , and the phase, Ψ of the ansatz.

PN correction factors: 2D problem (II)

Method: Compute analytically \mathcal{R}_Ω , i.e., the difference between the configuration perturbing p_r and p_t and the unperturbed configuration with $e = 0$.

- As a result one obtains (details in an upcoming paper),

$$\lambda_t = 1 + \left[\frac{B}{4\Omega_0} - \frac{B(3\eta+1)}{8r_0 c^2 \Omega_0} \right] \cos \Psi,$$

$$\lambda_r = 1 + \frac{B\eta}{2r_0^{1/2} \Omega_0 |p_r^0|} \left[1 + \frac{1}{r_0 c^2} \right] \sin \Psi.$$

$$\delta r = \frac{Br_0}{2\Omega_0} - \frac{3B(3+\eta)}{4c^2 \Omega_0}$$

where $\eta = m_1 m_2 / (m_1 + m_2)^2$, Ω_0 is the orbital frequency of QC orbits and p_r^0 is the initial radial momentum.

Results. Application to PN (I)

- Solve numerically 3.5PN Hamilton equations in ADMTT gauge.

$$\frac{d\mathbf{X}}{dt} = \frac{\partial H}{\partial \mathbf{P}}, \quad \frac{d\mathbf{P}}{dt} = -\frac{\partial H}{\partial \mathbf{X}} + \mathbf{F}.$$

with \mathbf{X} and \mathbf{P} the position and the momentum vectors, in the CM frame, H the Hamiltonian and \mathbf{F} is the radiation reaction force.

- To compute the orbital frequency from the simulations we use

$$\Omega = |\vec{\Omega}| = \frac{|\vec{r} \times \vec{v}|}{r^2},$$

where \vec{r} is the position vector in the CM frame, $r = |\vec{r}|$, and \vec{v} is the velocity vector.

Results. Application to PN (II)

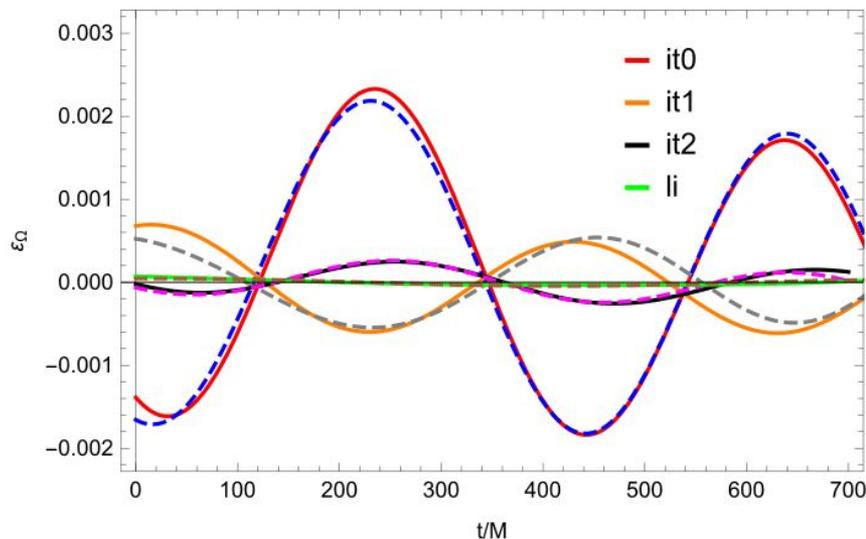
- Test configuration: $q = 4$, $\chi_{1z} = 0.8$, $\chi_{2z} = -0.8$, $D = 12M$
- Sign correction **+1/-1** depending behaviour residual at origin.

Post-Circular correcting for (λ_t, λ_r)					
Iteration	$(\varepsilon_\Omega \pm \delta\varepsilon_\Omega) \cdot 10^{-3}$	$10 \cdot p_t$	$p_r \cdot 10^3$	λ_t	λ_r
0	1.973 ± 0.006	0.56477	0.238712	1.00085	1.19247
1	0.561 ± 0.015	0.56529	0.284657	0.99974	0.94794
2	0.221 ± 0.007	0.56516	0.271206		
Post-Post-Circular correcting for (λ_t, λ_r)					
Iteration	$(\varepsilon_\Omega \pm \delta\varepsilon_\Omega) \cdot 10^{-3}$	$10 \cdot p_t$	$p_r \cdot 10^3$	λ_t	λ_r
0	0.833 ± 0.005	0.56517	0.238712	1.00013	1.19737
1	0.567 ± 0.003	0.56525	0.285827	0.99974	0.96201
2	0.197 ± 0.005	0.56510	0.274971		
Post-Circular correcting for $(\delta r, \lambda_r)$					
Iteration	$(\varepsilon_\Omega \pm \delta\varepsilon_\Omega) \cdot 10^{-3}$	D	$p_r \cdot 10^3$	δr	λ_r
0	1.973 ± 0.006	12.0	0.238712	0.01432	1.19247
1	0.718 ± 0.004	12.0143	0.284657	0.00445	0.999083
2	0.230 ± 0.003	12.0099	0.284396		

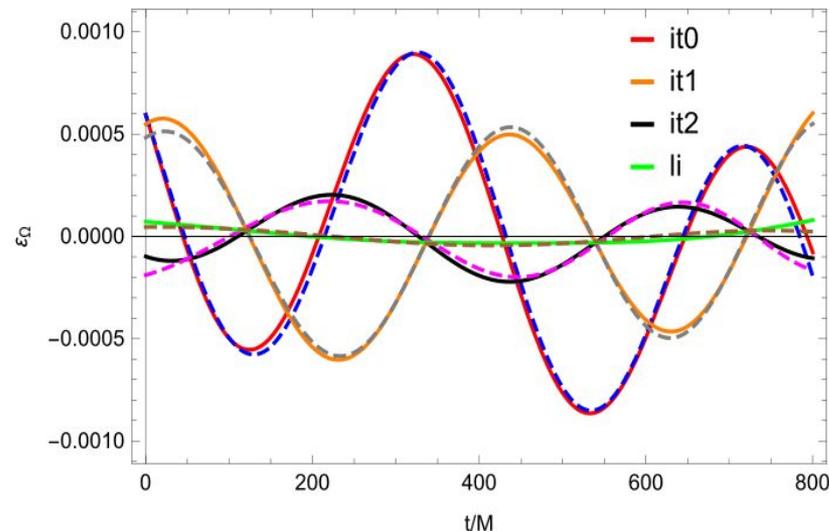
Results. Application to PN (III)

$$q = 4, \chi_{1z} = 0.8, \chi_{2z} = -0.8, D = 12M$$

Post-circular



Post-Post-circular



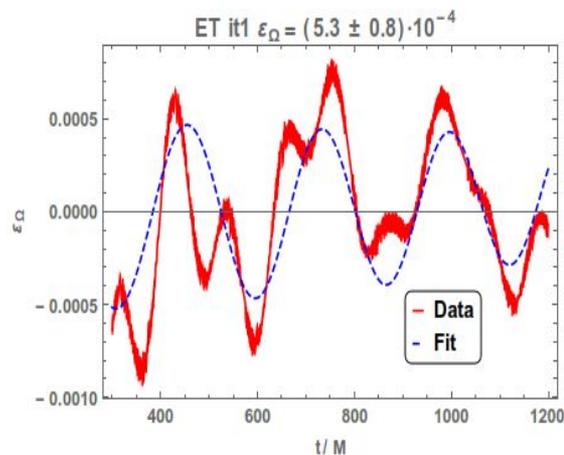
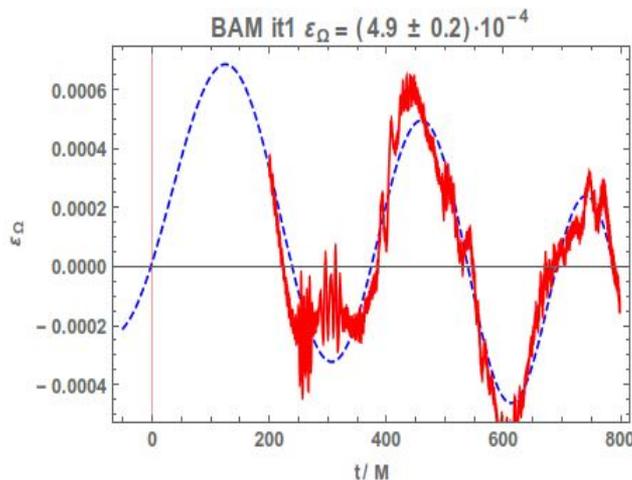
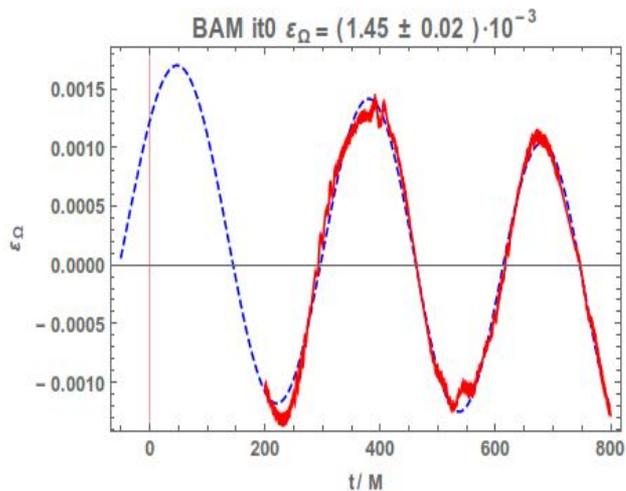
- Long integration ($D=30M$) best result, but unpractical for precessing systems.
- Procedure also tested in precessing PN with similar results.

Results. NR set up

- We use ET and BAM (Sascha's talk) codes.
- Both implement a moving puncture version of the BSSN formulation of the Einstein equations.
- Initial burst of junk radiation \rightarrow neglect data until $\sim 200M$.
- For ET we use the multipatch Llama thorn: regular cartesian near zone and adapted spherical grids covering the wave zone.
- To avoid gauge oscillations \rightarrow η parameter appearing in the Γ -driver shift condition to 0.25 for simulations used to reduce the eccentricity and 1 for the production ones.

Results. NR example

- Ex. : $q = 2$; $\chi_1 = \{0., 0., 0.\}$; $\chi_2 = \{0.353553, 0.353553, 0.5\}$; $d_0 = 10.8M$
- We use PC initial data. Low resolution $N=64$ and $\eta = 0.25$



Results. NR initial iteration (I)

- NR and PN different coordinates \rightarrow They agree up to 2PN in ADMTT gauge (*Tichy et al 2002*).
- Test what works better in NR PC or PPC for 12 configurations.
- All BAM simulations at low resolution (N=64).

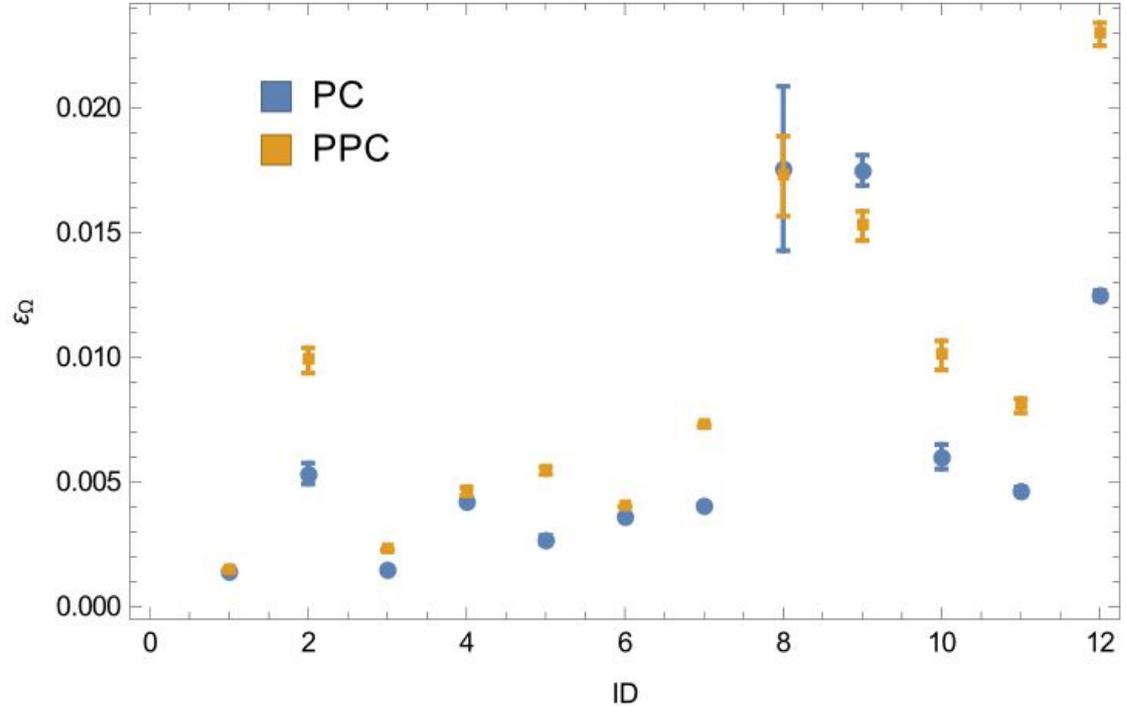
Results. NR initial iteration (II)

ID	Approx.	q	$\vec{\chi}_1$	$\vec{\chi}_2$	D/M	$(\varepsilon_\Omega \pm \delta\varepsilon_\Omega) \cdot 10^3$
1	PC	1	(0, 0, 0)	(0, 0, 0)	11	1.42 ± 0.02
1	PPC	1	(0, 0, 0)	(0, 0, 0)	11	1.43 ± 0.04
2	PC	1	(0, 0, -0.5)	(0, 0, -0.5)	11	5.3 ± 0.4
2	PPC	1	(0, 0, -0.5)	(0, 0, -0.5)	11	9.8 ± 0.5
3	PC	1	(0, 0, 0.5)	(0, 0, -0.5)	11	1.5 ± 0.05
3	PPC	1	(0, 0, 0.5)	(0, 0, -0.5)	11	2.27 ± 0.04
4	PC	2	(0, 0, -0.75)	(0, 0, -0.75)	12.6	4.22 ± 0.07
4	PPC	2	(0, 0, -0.75)	(0, 0, -0.75)	12.6	4.61 ± 0.16
5	PC	2	(0, 0, 0)	$\vec{\alpha}$	10.8	2.68 ± 0.17
5	PPC	2	(0, 0, 0)	$\vec{\alpha}$	10.8	5.43 ± 0.13
6	PC	2	(0, 0, 0)	$\vec{\beta}$	10.8	3.61 ± 0.017
6	PPC	2	(0, 0, 0)	$\vec{\beta}$	10.8	4.003 ± 0.018
7	PC	4	(0, 0, -0.8)	(0, 0, 0.8)	11	4.05 ± 0.07
7	PPC	4	(0, 0, -0.8)	(0, 0, 0.8)	11	7.25 ± 0.06
8	PC	4	(0, 0, -0.8)	(0, 0, -0.8)	11	17.9 ± 1.5
8	PPC	4	(0, 0, -0.8)	(0, 0, -0.8)	11	17.5 ± 1.5
9	PC	4	(0, 0, 0.8)	(0, 0, -0.8)	11	17.4 ± 0.6
9	PPC	4	(0, 0, 0.8)	(0, 0, -0.8)	11	15.3 ± 0.5
10	PC	4	(0, 0, 0.8)	(0, 0, 0.8)	11	5.5 ± 0.5
10	PPC	4	(0, 0, 0.8)	(0, 0, 0.8)	11	9.9 ± 0.6
11	PC	8	(0, 0, 0.5)	(0, 0, -0.5)	11	4.64 ± 0.14
11	PPC	8	(0, 0, 0.5)	(0, 0, -0.5)	11	8.0 ± 0.2
12	PC	8	(0, 0, -0.5)	(0, 0, -0.5)	11	12.49 ± 0.18
12	PPC	8	(0, 0, -0.5)	(0, 0, -0.5)	11	22.9 ± 0.4

$$\vec{\alpha} = (0.3535, -0.3535, -0.5), \quad \vec{\beta} = (0.3535, -0.3535, 0.5)$$

Results. NR initial iteration (III)

- One observes that PC initial data work better in NR than PPC. (except for ID9)

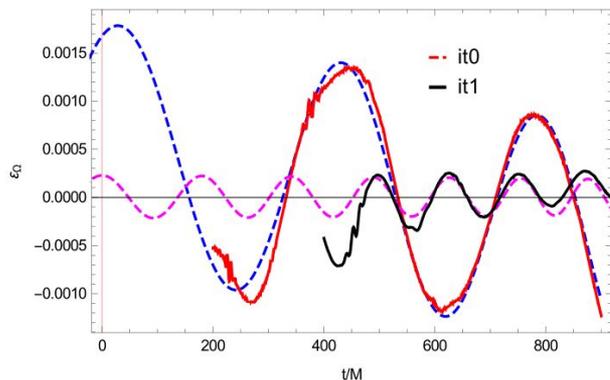


Results. Reduced NR simulations (I)

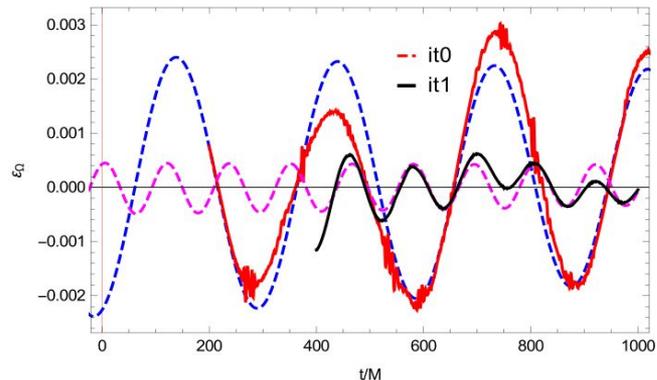
ID	Iteration	Code	N	η	q	$\vec{\chi}_1$	$\vec{\chi}_2$	D/M	$10 \cdot p_t$	$10^3 \cdot p_r$	λ_t	λ_r	$(\varepsilon_\Omega \pm \delta\varepsilon_\Omega) \cdot 10^3$
1	0	BAM	64	0.25	1	(0, 0, 0)	(0, 0, 0)	12	0.850941	0.53833	0.9997	0.8695	1.42 ± 0.02
	1	BAM	96	0.25	1	(0, 0, 0)	(0, 0, 0)	12	0.850686	0.468113			0.22 ± 0.02
13	0	BAM	64	0.25	1	(0, 0, -0.5)	(0, 0, 0.5)	11	0.901836	0.722706	0.9998	0.8581	1.24 ± 0.03
	1	BAM	64	0.25	1	(0, 0, -0.5)	(0, 0, 0.5)	11	0.901688	0.620187			0.27 ± 0.02
14	0	BAM	64	0.25	1	(0, 0, 0.5)	(0, 0, 0.5)	11	0.874251	0.601797	0.999237	0.9346	1.64 ± 0.03
	1	BAM	64	0.25	1	(0, 0, 0.5)	(0, 0, 0.5)	11	0.873583	0.562465			0.39 ± 0.03
15	0	ET	64	0.24	1.5	(0, 0, -0.6)	(0, 0, 0.6)	10.8	0.868557	0.699185	0.999737	0.9168	1.12 ± 0.05
	1	ET	80	0.24	1.5	(0, 0, -0.6)	(0, 0, 0.6)	10.8	0.856941	0.641051			0.84 ± 0.165
16	0	ET	64	0.2314	1.75	(0, 0, 0.6)	(0, 0, -0.6)	10.8	0.856941	0.685199	0.999643	0.8525	1.52 ± 0.08
	1	ET	80	0.2314	1.75	(0, 0, 0.6)	(0, 0, -0.6)	10.8	0.856636	0.584173			0.43 ± 0.07
17	0	ET	64	0.2314	1.75	(0, 0, -0.6)	(0, 0, 0.6)	10.8	0.834827	0.649957	0.999903	0.8941	1.12 ± 0.14
	1	ET	80	0.2314	1.75	(0, 0, -0.6)	(0, 0, 0.6)	10.8	0.834746	0.581178			0.66 ± 0.13
18	0	BAM	64	0.2222	2	(0, 0, 0.75)	(0, 0, 0.75)	11.1117	0.760924	0.450647	0.999937	0.6566	2.38 ± 0.07
	1	BAM	96	0.2222	2	(0, 0, 0.75)	(0, 0, 0.75)	11.1117	0.760876	0.295898			0.47 ± 0.05
19	0	BAM	80	0.1875	3	(0, 0, 0)	(0, 0, 0)	10	0.72377	0.575703	0.999914	0.8629	1.41 ± 0.07
	1	BAM	64	0.1875	3	(0, 0, 0)	(0, 0, 0)	10	0.723708	0.496774			0.29 ± 0.24
7	0	BAM	64	0.16	4	(0, 0, -0.8)	(0, 0, 0.8)	11	0.559207	0.336564	0.998501	0.7341	4.05 ± 0.07
	1	BAM	64	0.16	4	(0, 0, -0.8)	(0, 0, 0.8)	11	0.558369	0.24708			0.45 ± 0.4
20	0	BAM	64	0.0987	8	(0, 0, 0.5)	(0, 0, 0.5)	11	0.102969	0.345755	1.00066	1.3512	2.2 ± 0.4
	1	BAM	64	0.0987	8	(0, 0, 0.5)	(0, 0, 0.5)	11	0.139132	0.345985			0.45 ± 0.4
21	0	BAM	64	0.2222	2	(0, 0, 0)	(0.4949, 0.4949, 0)	10.8	0.811783	0.649957	0.999788	0.9802	6.4 ± 1.7
	1	ET	80	0.2222	2	(0, 0, 0)	(0.4949, 0.4949, 0)	10.8	0.811611	0.581178			0.40 ± 0.05
22	0	BAM	64	0.2222	2	(0, 0, 0)	(0.1767, 0.1767, 0)	10.8	0.812379	0.610965	0.999534	0.9009	1.46 ± 0.02
	1	ET	80	0.2222	2	(0, 0, 0)	(0.1767, 0.1767, 0)	10.8	0.812001	0.550427			0.54 ± 0.05
23	0	ET	64	0.2222	2	(0, 0, 0)	(-0.1767, 0.1767, 0.5)	10.8	0.793749	0.53149	0.99994	0.881549	1.88 ± 0.01
	1	ET	80	0.2222	2	(0, 0, 0)	(-0.1767, 0.1767, 0.5)	10.8	0.793701	0.468535			0.28 ± 0.05
24	0	ET	64	0.2222	2	(0, 0, 0)	(-0.3535, 0.3535, 0.5)	10.8	0.7935	0.531374	0.999772	0.843376	2.13 ± 0.03
	1	ET	80	0.2222	2	(0, 0, 0)	(-0.3535, 0.3535, 0.5)	10.8	0.79332	0.448148			0.48 ± 0.05
25	0	ET	64	0.2222	2	(0, 0, 0)	(-0.3535, 0.3535, 0.)	10.8	0.812118	0.611108	0.999848	0.895657	1.78 ± 0.07
	1	ET	80	0.2222	2	(0, 0, 0)	(-0.3535, 0.3535, 0.)	10.8	0.811994	0.547343			0.69 ± 0.07

Results. Reduced NR simulations (II)

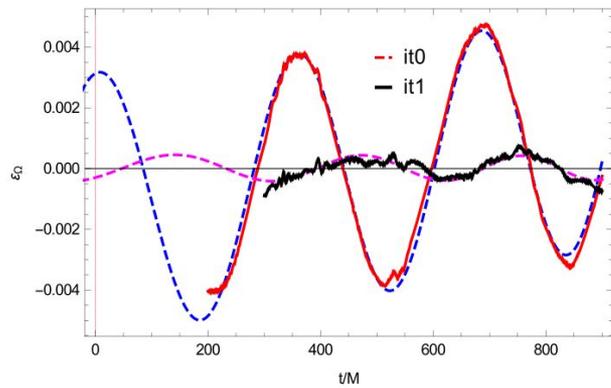
$q1_ (0, 0, 0)_ (0, 0, 0)_ D12$



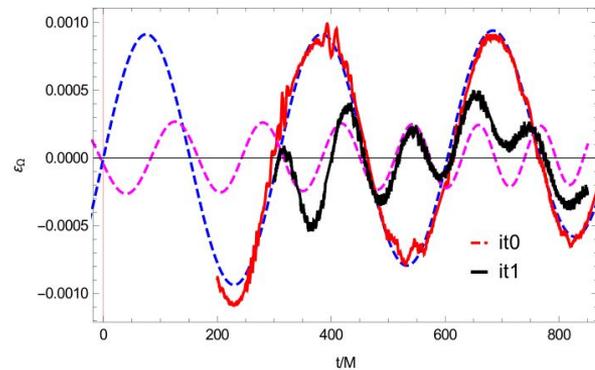
$q2_ (0, 0, 0.75)_ (0, 0, 0.75)_ D11.1117$



$q4_ (0, 0, -0.8)_ (0, 0, 0.8)_ D11$



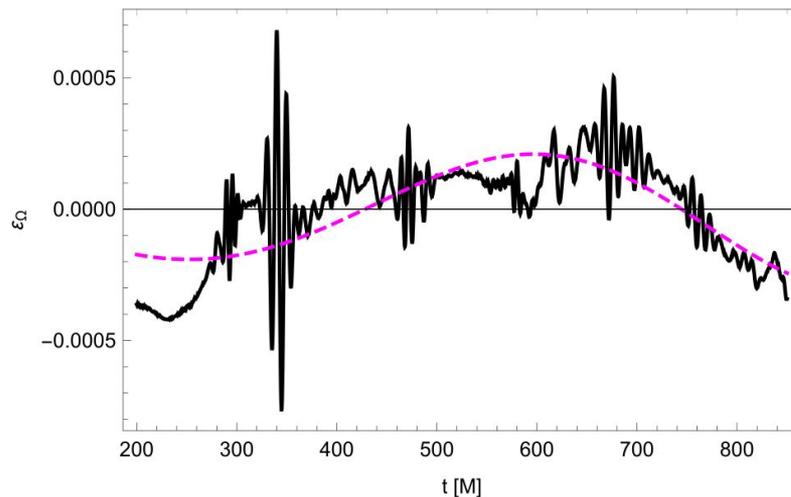
$q2_ (0, 0, 0)_ (-0.17, 0.17, 0.5)_ D10.8$



Results. NR separation correction (I)

- We test also the separation correction in NR.
- For the configuration ID2, $q = 1$, $\chi_{1z} = -0.5$, $\chi_{2z} = 0.5$, $D = 11M$

Iteration	Code	N	δr	λ_r	$(\varepsilon_\Omega \pm \delta\varepsilon_\Omega) \cdot 10^{-3}$
0	BAM	64			1.24 ± 0.03
1	BAM	64	-0.0023	0.8581	0.2 ± 0.2



Conclusions

- PN based method to reduce eccentricity from numerical simulations.
- Method tested for two different moving puncture binary black hole evolution codes (ET and BAM).
- Method tested for different mass ratios and spin orientations.
- The method provides eccentricities of $O(10^{-4})$ in one iteration.
- **Limitations:** short evolutions unable an accurate eccentricity measurement, the higher the initial eccentricity the more iteration will be needed.

- Open questions: could the method work for spectral codes? could the method work for neutron star simulations?