

# Simple method to reduce the eccentricity of Binary Black Hole simulations with the EinsteinToolkit

A. Ramos Buades, Sascha Husa, Geraint Pratten

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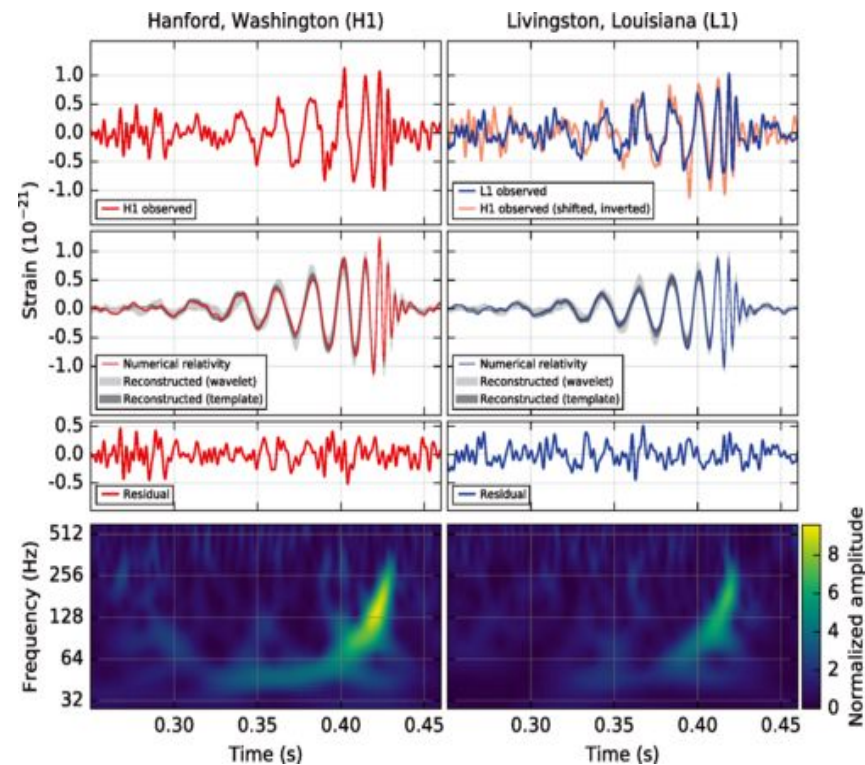
Universitat  
de les Illes Balears

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# Introduction. Gravitational wave motivation

- Current GW observations from BBHs coalescences are compatible with low eccentricity systems.
- Most of the binary systems are expected to have circularized by the time their GW signals enter the frequency band of the LIGO and Virgo detectors.



# Introduction. Framework

- Eccentricity Reduction  $\rightarrow$  within the phenomenological waveform modelling efforts. (Geraint's talk)
- BBH simulations are run with BAM and ET codes to get waveforms.
- Imperfections of NR initial data  $\rightarrow$  waveforms with residual eccentricity.
- **Main Objective:** Establish a systematic procedure to reduce eccentricity.

# Initial data for NR simulations of BBH

- 1) Choose  $r$  and  $\vec{S}_1, \vec{S}_2$  .
- 2) Choose  $\vec{p}/\vec{v}$  of the BH such to result in low eccentricity. (PN approximations)
- 3) Solve numerically the constraints equations. (usually conformal flatness)
- 4) Evolve data numerically until eccentricity can be measured reliably from oscillations in  $r, \phi, \omega, \phi_{22}, \omega_{22}, \dots$
- 5) A correction to the initial parameters is applied, and steps 2-5 (or 1-5) are applied until eccentricity is low enough for applications.

# Introduction. Eccentricity estimators

- In numerical simulations, small eccentricity  $\rightarrow$  small residual oscillations with amplitude proportional to the eccentricity are added monotonically changing orbital variables.
- In GR no unique definition of the eccentricity!
- Quantities such as the orbital frequency get eccentricity as

$$\Omega(t) = D(t) + e_{\Omega}(t) \cos(\Omega_r t) \quad (1)$$

- We define an eccentricity estimator of the form

$$e_{\Omega} = \frac{\Omega(t) - \Omega_{fit}(t)}{2\Omega_{fit}(t)} \quad (2)$$

Election based on the nearly gauge-independence of the orbital frequency,  $\Omega$ .

# Introduction. Iterative methods

- Iterative schemes  $\rightarrow$  Most efficient way to reduce  $e_t$  from numerical simulations.
- Given initial config.  $(r_0, p_r^0, p_t^0, \chi_1, \chi_2)$  modify  $(p_r^0, p_t^0/r_0)$  to reduce the eccentricity .
- Summary:
  - 1) Provide initial values for  $(p_r^0, p_t^0, r_0)$  data at a given separation/orbital freq.
  - 2) Measure the eccentricity  $e_0$  from the simulation.
  - 3) Use  $e_0$  to compute  $(\lambda_r, \lambda_t/\delta_r)$ .
  - 4) Apply the correction factors:
$$\begin{array}{ll} p_r^1 = \lambda_r^0 p_r^0 & p_r^1 = \lambda_r^0 p_r^0, \\ p_t^1 = \lambda_t^0 p_t^0 & r_1 = r_0 + \delta r \end{array}$$
  - 5) Run the a simulation with the new parameters and measure the eccentricity  $e_1$  from the new simulation.
  - 6) If the eccentricity is not low enough go to step 3).

# Eccentricity measurement (I)

- A fit to the data (NR or PN) is necessary to compute  $e_{\Omega}(t)$ . (*Mathematica NonlinearModelFit function*)
- We use an Ansatz based on the TaylorT3 approximant [Buonanno et al. Phys.Rev.D80,084043(2009)]

$$\begin{aligned}\theta &= [\eta |T_{\text{merg}} t_0 - t|/5]^{-1/8} \\ A &= \frac{a_1 \theta^3}{16\pi} (1 + b_2 \theta^2 + b_3 \theta^3 + b_4 \theta^4 + b_5 \theta^5 + b_6 \theta^6) \\ \text{ansatz} &= A + a_6 \cos(\Omega_0 \omega_1 t + t_1)\end{aligned}$$

- $T_{\text{merg}}$  is an scale of the merger time.
- $b_2, b_3, b_4, b_5, b_6 \rightarrow$  analytical coefficients from TaylorT3.
- $t_0, a_1, a_6, \omega_1, t_1$  are unknown coefficients to fit.
- $\Omega_0$  is the 3.5PN orbital frequency for quasi-circular orbits.

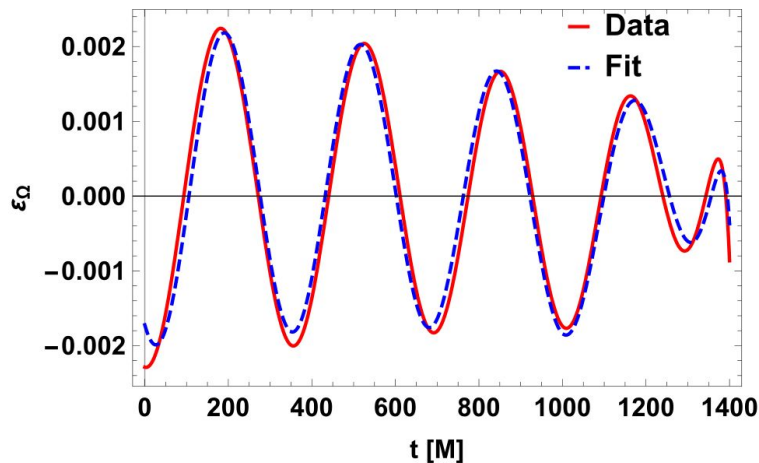
# Eccentricity measurement (II)

- The ansatz can be identified with the residual between the data and our model based on **3.5PN** approximant.

$$\mathcal{R}(t) = \Omega(t) - \Omega_0$$

- Once the model is fitted to data,  $e_\Omega$  can be calculated from the amplitude of the oscillations,

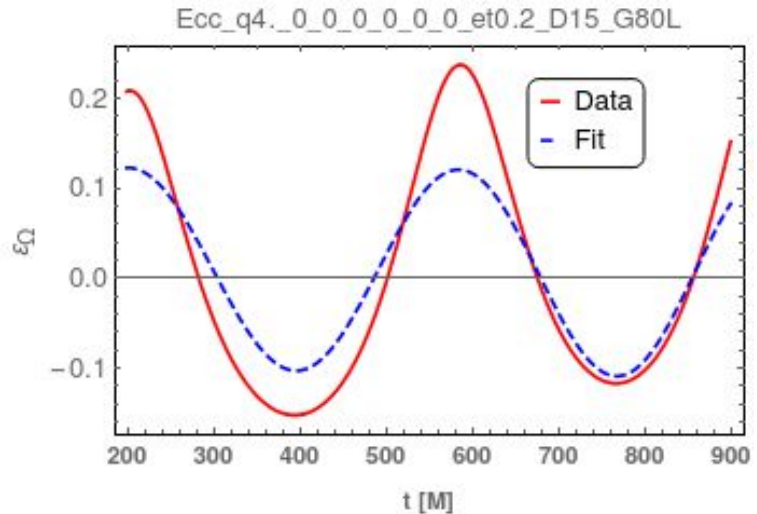
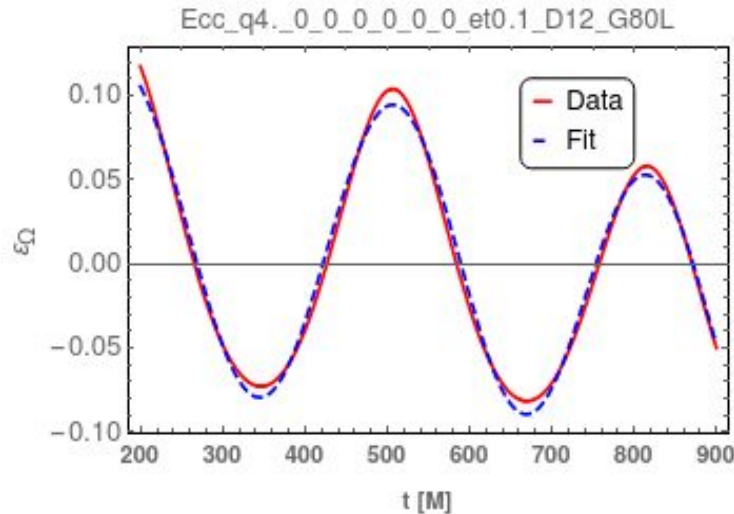
$$e_\Omega = \frac{1}{2} \frac{a_6}{\Omega_0}, \quad \delta e_\Omega = \frac{1}{2} \frac{\delta a_6}{\Omega_0}.$$





# Limit eccentricity measurement

- Eccentricity measurement tested to work up to  $e \sim 0.1$
- For higher eccentricities ansatz must be a sum of harmonics.



# PN Initial data. Introduction

**First step:** Provide low eccentric initial values for  $(r_0, p_r^0, p_t^0)$ .

- Use PN theory (slow motion, weak field regime) to derive analytical formulas for  $p_r(r, \eta, \chi_1, \chi_2)$  and  $p_t(r, \eta, \chi_1, \chi_2)$ .  $\eta = m_1 m_2 / (m_1 + m_2)^2$
- From PN Hamiltonians in ADMTT gauge up to 3.5PN, we compute analytical expressions for  $\Omega, p_r, p_t$ .

$$H = H_{orb} + H_{SO} + H_{SS} + H_{SSS},$$

$$p_r = 0, \quad \left( \frac{\partial H}{\partial r} \right)_{p_r=0} = 0.$$

- Once computed  $p_t(r)$ , then, one can compute the orbital frequency as

$$\Omega = \left( \frac{\partial H}{\partial p_\phi} \right)_{p_r=0}.$$

- The computation of  $p_r$  requires the gravitational wave energy flux,

$$-\frac{dE_{GW}}{dt} = \frac{dM}{dt} + \frac{dH_{circ}}{dt}.$$

# PN initial data. Postcircular Initial data

- Using the chain rule

$$\frac{dH_{circ}}{dt} = \left(\frac{dr}{dt}\right) \left(\frac{dH_{circ}}{dr}\right) \rightarrow \left(\frac{dr}{dt}\right) \approx \frac{-\frac{dE_{GW}}{dt}}{\left(\frac{dH_{circ}}{dr}\right)}.$$

- The procedure to obtain a postcircular (PC) expression for  $p_r$  can be summarized in the following algorithm:

1. Compute the circular expression for  $p_t(r)$  .
2. Use the expression for  $p_t(r)$  and  $p_r = 0$  to compute  $dH_{circ}/dr$  .
3. Combine  $dH_{circ}/dr$  with the GW flux for the QC orbits,  $dE_{GW}/dt$ , to obtain  $dr/dt$  .
4. Use Hamilton's equations to compute  $dr/dt = \partial H / \partial p_r$ . Taylor expand at first order in  $p_r$  of the RHS and isolate  $p_r$  as a function of  $dr/dt$  .
5. From step 4 compute an expression of  $p_r$  using the value of  $dr/dt$  calculated in step 3.

# PN initial data. Postpostcircular Initial data

- Extensively used to construct initial data for EOB dynamics.
- It describes a prescription to compute  $p_t$  using the PC information.
- Start with the Hamilton's equation for the radial momentum

$$\frac{dp_r}{dt} = - \frac{\partial H}{\partial r}.$$

- LHS of can be approximated using the chain rule and the PC solution to

$$\frac{dp_r}{dt} = \frac{dp_r}{dr} \frac{dr}{dt} \approx \frac{dp_r^{PC}}{dr} \frac{dr}{dt} = \frac{dp_r^{PC}}{dr} \frac{\partial H}{\partial p_r}.$$

- Combining these equations we get: 
$$- \left[ \frac{\partial H}{\partial r} \right]_{p_r=p_r^{PC}} \approx \left( \frac{dp_r^{PC}}{dr} \right) \left[ \frac{\partial H}{\partial p_r} \right]_{p_r=p_r^{PC}}.$$
- Given  $p_r, r, m_1, m_2, \vec{\chi}_1, \vec{\chi}_2$ ; one can solve for  $p_t$  using a root finding method.

# PN correction factors. Introduction (I)

- When PC and PPC initial data produce a simulation with non-negligible eccentricity  $\rightarrow$  iterative step is needed.
- Initial linear momenta corrections:  $(p_t, p_r) \rightarrow (\lambda_t p_t, \lambda_r p_r)$ .
- One can also choose:  $(r, p_r) \rightarrow (r + \delta r, \lambda_r p_r)$ .
- We provide analytical expressions to compute  $\lambda_t, \lambda_r, \delta r$ .
- Computations based on the Quasi-Keplerian 1PN equations of motion.

$$n_t(t - t_0) = u - e_t \sin u,$$

$$(\phi - \phi_0) = (1 + k)A_{e_\phi}(u),$$

$$A_{e_\phi}(u) = 2 \arctan \left[ \left( \frac{1 + e_\phi}{1 - e_\phi} \right)^{1/2} \right],$$

$$r = a_r(1 - e_r \cos u),$$

- $e_t, e_r, e_\phi$  are the temporal, radial and angular eccentricities,  $n_t$  is called the mean anomaly,  $u$  is the true anomaly and  $k$  is the fractional periastron advance per orbit.

# PN correction factors. Introduction (II)

- From QK eqs. at 1PN the radial coordinate,  $r$ , and the orbital frequency,  $\Omega = \dot{\phi}$  up to linear order in eccentricity are:

$$r = a_r (1 - e_r \cos[\Omega_r t]),$$

$$\Omega \equiv \dot{\phi} = \Omega_\phi (1 + (e_\phi + e_t) \cos[\Omega_r t]).$$

- We define an eccentricity estimator for the orbital frequency as

$$e_\Omega = \frac{\Omega(t) - \Omega(e=0)}{2\Omega(e=0)}$$

Introducing eq. for  $\Omega$  in eq. for  $e_\Omega$ , one gets

$$e_\Omega = \frac{e_\phi + e_t}{2}.$$

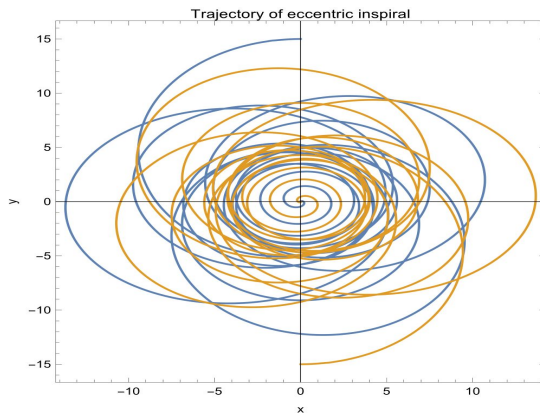
# PN correction factors: 1D problem

- From the 1PN QK solution of the equations of motion one can obtain an estimate of the correction factor for  $p_t$ .

$$\lambda_t = 1 + \frac{e_\Omega}{2} - \frac{e_\Omega}{2rc^2}(\eta + 2).$$

- Details of the computation in the upcoming paper (Ramos et al 2018).
- 1D computation limiting. Not able to reduce the eccentricity over some threshold.

- This equation can be used to generate eccentric NR simulation given a desired eccentricity (at leading order).



# PN correction factors: 2D problem (I)

- 2D problem  $(\lambda_t, \lambda_r)$  or  $(\delta r, \lambda_r)$  : follow another procedure.
- **Main goal:** fit the data using an ansatz made of **2 components**: a **non-eccentric** part + an **oscillatory** one.
- Hence, the relative oscillations in  $\Omega$  can be fitted using an ansatz like

$$\mathcal{R}_\Omega = A + B \cos(\Omega_r t + \Psi),$$

where  $\Omega_r$  is the frequency of the radial oscillations, and  $A, B, \Psi$  are coefficients to be determined.

- We have derived analytical expressions for  $\lambda_t, \lambda_r, \delta r$  in terms of the amplitude,  $B$ , and the phase,  $\Psi$  of the ansatz.



# PN correction factors: 2D problem (II)

**Method:** Compute analytically  $\mathcal{R}_\Omega$ , i.e., the difference between the configuration perturbing  $p_r$  and  $p_t$  and the unperturbed configuration with  $e = 0$ .

- As a result one obtains (details in an upcoming paper),

$$\lambda_t = 1 + \left[ \frac{B}{4\Omega_0} - \frac{B(3\eta+1)}{8r_0 c^2 \Omega_0} \right] \cos \Psi,$$

$$\lambda_r = 1 + \frac{B\eta}{2r_0^{1/2} \Omega_0 |p_r^0|} \left[ 1 + \frac{1}{r_0 c^2} \right] \sin \Psi.$$

$$\delta r = \frac{Br_0}{2\Omega_0} - \frac{3B(3+\eta)}{4c^2 \Omega_0}$$

where  $\eta = m_1 m_2 / (m_1 + m_2)^2$ ,  $\Omega_0$  is the orbital frequency of QC orbits and  $p_r^0$  is the initial radial momentum.

# Results. Application to PN (I)

- Solve numerically 3.5PN Hamilton equations in ADMTT gauge.

$$\frac{d\mathbf{X}}{dt} = \frac{\partial H}{\partial \mathbf{P}}, \quad \frac{d\mathbf{P}}{dt} = -\frac{\partial H}{\partial \mathbf{X}} + \mathbf{F}.$$

with  $\mathbf{X}$  and  $\mathbf{P}$  the position and the momentum vectors, in the CM frame,  $H$  the Hamiltonian and  $\mathbf{F}$  is the radiation reaction force.

- To compute the orbital frequency from the simulations we use

$$\Omega = |\vec{\Omega}| = \frac{|\vec{r} \times \vec{v}|}{r^2},$$

where  $\vec{r}$  is the position vector in the CM frame,  $r = |\vec{r}|$ , and  $\vec{v}$  is the velocity vector.

# Results. Application to PN (II)

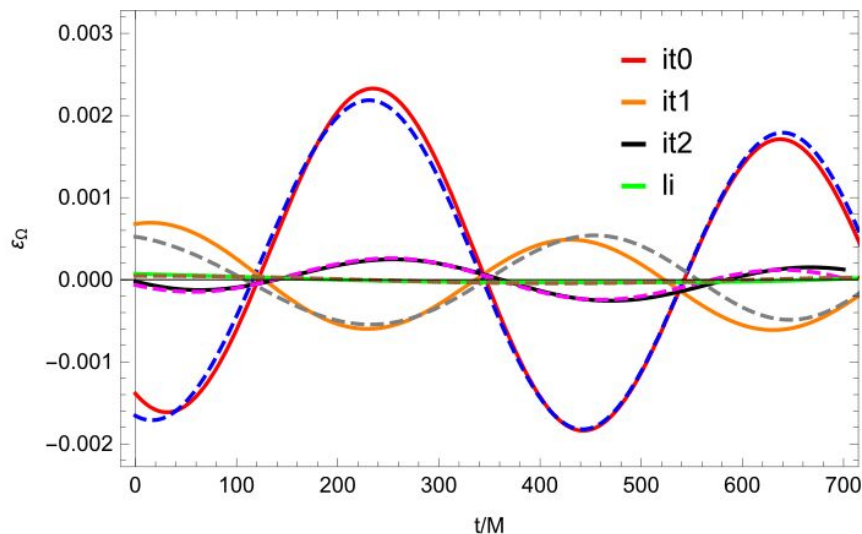
- Test configuration:  $q = 4, \chi_{1z} = 0.8, \chi_{2z} = -0.8, D = 12M$
- Sign correction **+1/-1** depending behaviour residual at origin.

Post-Circular correcting for $(\lambda_t, \lambda_r)$					
Iteration	$(\varepsilon_\Omega \pm \delta\varepsilon_\Omega) \cdot 10^{-3}$	$10 \cdot p_t$	$p_r \cdot 10^3$	$\lambda_t$	$\lambda_r$
0	$1.973 \pm 0.006$	0.56477	0.238712	1.00085	1.19247
1	$0.561 \pm 0.015$	0.56529	0.284657	0.99974	0.94794
2	$0.221 \pm 0.007$	0.56516	0.271206		
Post-Post-Circular correcting for $(\lambda_t, \lambda_r)$					
Iteration	$(\varepsilon_\Omega \pm \delta\varepsilon_\Omega) \cdot 10^{-3}$	$10 \cdot p_t$	$p_r \cdot 10^3$	$\lambda_t$	$\lambda_r$
0	$0.833 \pm 0.005$	0.56517	0.238712	1.00013	1.19737
1	$0.567 \pm 0.003$	0.56525	0.285827	0.99974	0.96201
2	$0.197 \pm 0.005$	0.56510	0.274971		
Post-Circular correcting for $(\delta r, \lambda_r)$					
Iteration	$(\varepsilon_\Omega \pm \delta\varepsilon_\Omega) \cdot 10^{-3}$	$D$	$p_r \cdot 10^3$	$\delta r$	$\lambda_r$
0	$1.973 \pm 0.006$	12.0	0.238712	0.01432	1.19247
1	$0.718 \pm 0.004$	12.0143	0.284657	0.00445	0.999083
2	$0.230 \pm 0.003$	12.0099	0.284396		

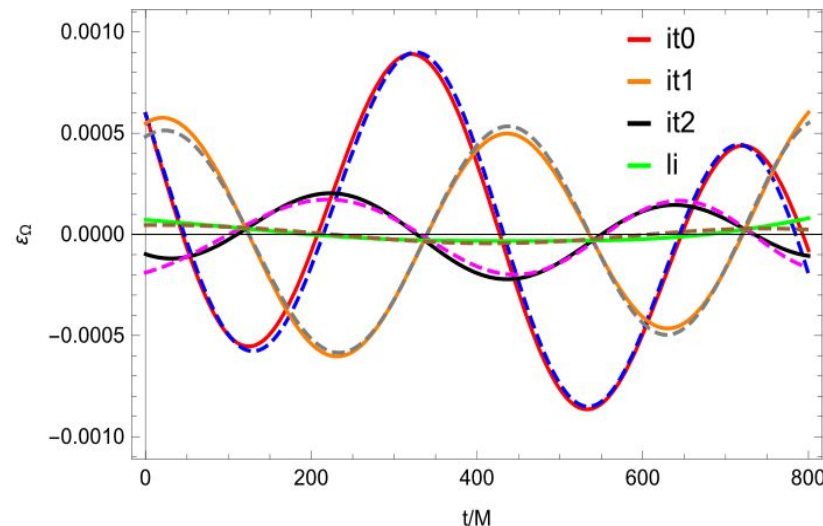
# Results. Application to PN (III)

$$q = 4, \chi_{1z} = 0.8, \chi_{2z} = -0.8, D = 12M$$

Post-circular



Post-Post-circular



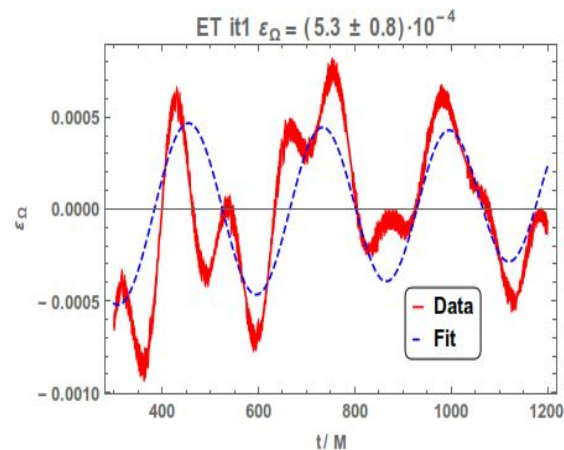
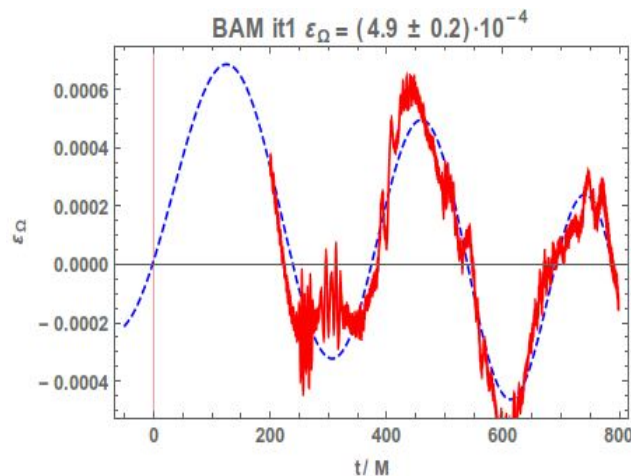
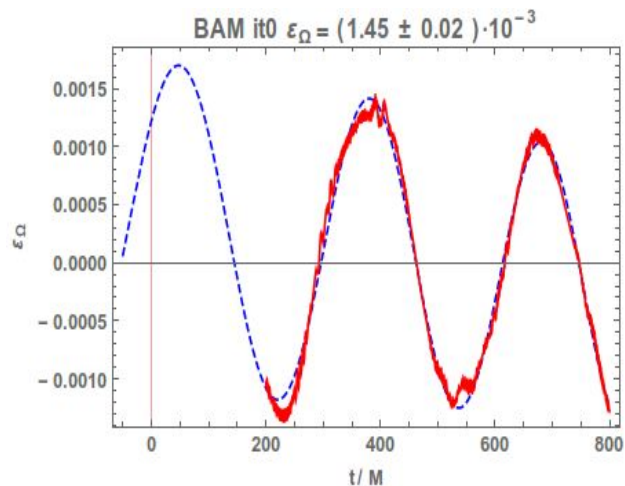
- Long integration ( $D=30M$ ) best result, but unpractical for precessing systems.
- Procedure also tested in precessing PN with similar results.

# Results. NR set up

- We use ET and BAM (Sascha's talk) codes.
- Both implement a moving puncture version of the BSSN formulation of the Einstein equations.
- Initial burst of junk radiation  $\rightarrow$  neglect data until  $\sim 200M$ .
- For ET we use the multipatch Llama thorn: regular cartesian near zone and adapted spherical grids covering the wave zone.
- To avoid gauge oscillations  $\rightarrow$   $\eta$  parameter appearing in the  $\Gamma$ -driver shift condition to 0.25 for simulations used to reduce the eccentricity and 1 for the production ones.

# Results. NR example

- Ex. :  $q = 2$ ;  $\chi_1 = \{0., 0., 0.\}$ ;  $\chi_2 = \{0.353553, 0.353553, 0.5\}$ ;  $d_0 = 10.8M$
- We use PC initial data. Low resolution  $N=64$  and  $\eta = 0.25$



# Results. NR initial iteration (I)

- NR and PN different coordinates  $\rightarrow$  They agree up to 2PN in ADMTT gauge (*Tichy et al 2002*).
- Test what works better in NR PC or PPC for 12 configurations.
- All BAM simulations at low resolution ( $N=64$ ).

# Results. NR initial iteration (II)

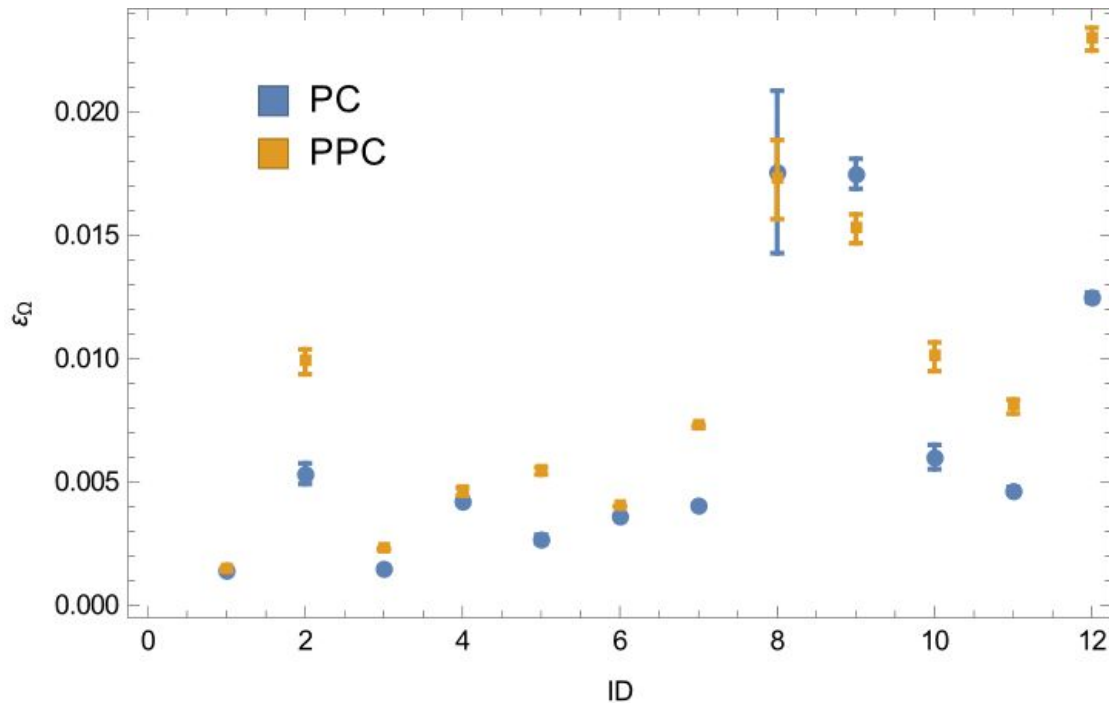
ID	Approx.	q	$\vec{\chi}_1$	$\vec{\chi}_2$	$D/M$	$(\varepsilon_\Omega \pm \delta\varepsilon_\Omega) \cdot 10^3$
1	PC	1	(0, 0, 0)	(0, 0, 0)	11	$1.42 \pm 0.02$
1	PPC	1	(0, 0, 0)	(0, 0, 0)	11	$1.43 \pm 0.04$
2	PC	1	(0, 0, -0.5)	(0, 0, -0.5)	11	$5.3 \pm 0.4$
2	PPC	1	(0, 0, -0.5)	(0, 0, -0.5)	11	$9.8 \pm 0.5$
3	PC	1	(0, 0, 0.5)	(0, 0, -0.5)	11	$1.5 \pm 0.05$
3	PPC	1	(0, 0, 0.5)	(0, 0, -0.5)	11	$2.27 \pm 0.04$
4	PC	2	(0, 0, -0.75)	(0, 0, -0.75)	12.6	$4.22 \pm 0.07$
4	PPC	2	(0, 0, -0.75)	(0, 0, -0.75)	12.6	$4.61 \pm 0.16$
5	PC	2	(0, 0, 0)	$\vec{\alpha}$	10.8	$2.68 \pm 0.17$
5	PPC	2	(0, 0, 0)	$\vec{\alpha}$	10.8	$5.43 \pm 0.13$
6	PC	2	(0, 0, 0)	$\vec{\beta}$	10.8	$3.61 \pm 0.017$
6	PPC	2	(0, 0, 0)	$\vec{\beta}$	10.8	$4.003 \pm 0.018$
7	PC	4	(0, 0, -0.8)	(0, 0, 0.8)	11	$4.05 \pm 0.07$
7	PPC	4	(0, 0, -0.8)	(0, 0, 0.8)	11	$7.25 \pm 0.06$
8	PC	4	(0, 0, -0.8)	(0, 0, -0.8)	11	$17.9 \pm 1.5$
8	PPC	4	(0, 0, -0.8)	(0, 0, -0.8)	11	$17.5 \pm 1.5$
9	PC	4	(0, 0, 0.8)	(0, 0, -0.8)	11	$17.4 \pm 0.6$
9	PPC	4	(0, 0, 0.8)	(0, 0, -0.8)	11	$15.3 \pm 0.5$
10	PC	4	(0, 0, 0.8)	(0, 0, 0.8)	11	$5.5 \pm 0.5$
10	PPC	4	(0, 0, 0.8)	(0, 0, 0.8)	11	$9.9 \pm 0.6$
11	PC	8	(0, 0, 0.5)	(0, 0, -0.5)	11	$4.64 \pm 0.14$
11	PPC	8	(0, 0, 0.5)	(0, 0, -0.5)	11	$8.0 \pm 0.2$
12	PC	8	(0, 0, -0.5)	(0, 0, -0.5)	11	$12.49 \pm 0.18$
12	PPC	8	(0, 0, -0.5)	(0, 0, -0.5)	11	$22.9 \pm 0.4$

$$\vec{\alpha} = (0.3535, -0.3535, -0.5), \quad \vec{\beta} = (0.3535, -0.3535, 0.5)$$



# Results. NR initial iteration (III)

- One observes that PC initial data work better in NR than PPC. (except for ID9)

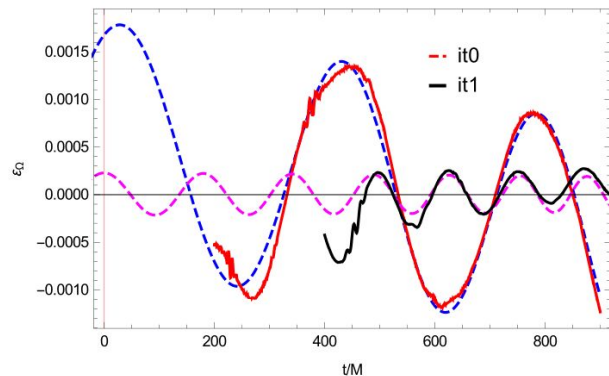


# Results. Reduced NR simulations (I)

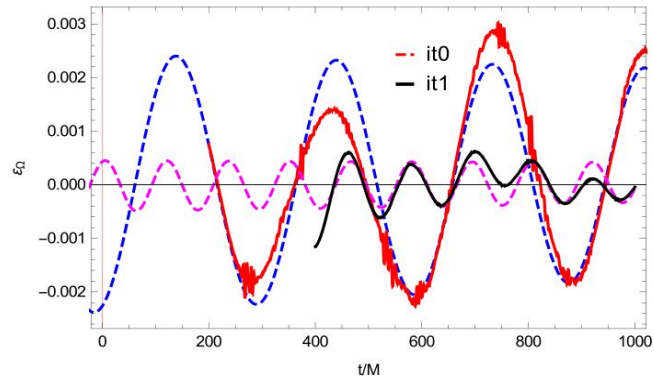
ID	Iteration	Code	N	$\eta$	q	$\vec{\chi}_1$	$\vec{\chi}_2$	$D/M$	$10 \cdot p_t$	$10^3 \cdot p_r$	$\lambda_t$	$\lambda_r$	$(\varepsilon_\Omega \pm \delta\varepsilon_\Omega) \cdot 10^3$
1	0	BAM	64	0.25	1	(0, 0, 0)	(0, 0, 0)	12	0.850941	0.53833	0.9997	0.8695	$1.42 \pm 0.02$
	1	BAM	96	0.25	1	(0, 0, 0)	(0, 0, 0)	12	0.850686	0.468113			$0.22 \pm 0.02$
13	0	BAM	64	0.25	1	(0, 0, -0.5)	(0, 0, 0.5)	11	0.901836	0.722706	0.9998	0.8581	$1.24 \pm 0.03$
	1	BAM	64	0.25	1	(0, 0, -0.5)	(0, 0, 0.5)	11	0.901688	0.620187			$0.27 \pm 0.02$
14	0	BAM	64	0.25	1	(0, 0, 0.5)	(0, 0, 0.5)	11	0.874251	0.601797	0.999237	0.9346	$1.64 \pm 0.03$
	1	BAM	64	0.25	1	(0, 0, 0.5)	(0, 0, 0.5)	11	0.873583	0.562465			$0.39 \pm 0.03$
15	0	ET	64	0.24	1.5	(0, 0, -0.6)	(0, 0, 0.6)	10.8	0.868557	0.699185	0.999737	0.9168	$1.12 \pm 0.05$
	1	ET	80	0.24	1.5	(0, 0, -0.6)	(0, 0, 0.6)	10.8	0.856941	0.641051			$0.84 \pm 0.165$
16	0	ET	64	0.2314	1.75	(0, 0, 0.6)	(0, 0, -0.6)	10.8	0.856941	0.685199	0.999643	0.8525	$1.52 \pm 0.08$
	1	ET	80	0.2314	1.75	(0, 0, 0.6)	(0, 0, -0.6)	10.8	0.856636	0.584173			$0.43 \pm 0.07$
17	0	ET	64	0.2314	1.75	(0, 0, -0.6)	(0, 0, 0.6)	10.8	0.834827	0.649957	0.999903	0.8941	$1.12 \pm 0.14$
	1	ET	80	0.2314	1.75	(0, 0, -0.6)	(0, 0, 0.6)	10.8	0.834746	0.581178			$0.66 \pm 0.13$
18	0	BAM	64	0.2222	2	(0, 0, 0.75)	(0, 0, 0.75)	11.1117	0.760924	0.450647	0.999937	0.6566	$2.38 \pm 0.07$
	1	BAM	96	0.2222	2	(0, 0, 0.75)	(0, 0, 0.75)	11.1117	0.760876	0.295898			$0.47 \pm 0.05$
19	0	BAM	80	0.1875	3	(0, 0, 0)	(0, 0, 0)	10	0.72377	0.575703	0.999914	0.8629	$1.41 \pm 0.07$
	1	BAM	64	0.1875	3	(0, 0, 0)	(0, 0, 0)	10	0.723708	0.496774			$0.29 \pm 0.24$
7	0	BAM	64	0.16	4	(0, 0, -0.8)	(0, 0, 0.8)	11	0.559207	0.336564	0.998501	0.7341	$4.05 \pm 0.07$
	1	BAM	64	0.16	4	(0, 0, -0.8)	(0, 0, 0.8)	11	0.558369	0.24708			$0.45 \pm 0.4$
20	0	BAM	64	0.0987	8	(0, 0, 0.5)	(0, 0, 0.5)	11	0.102969	0.345755	1.00066	1.3512	$2.2 \pm 0.4$
	1	BAM	64	0.0987	8	(0, 0, 0.5)	(0, 0, 0.5)	11	0.139132	0.345985			$0.45 \pm 0.4$
21	0	BAM	64	0.2222	2	(0, 0, 0)	(0.4949, 0.4949, 0)	10.8	0.811783	0.649957	0.999788	0.9802	$6.4 \pm 1.7$
	1	ET	80	0.2222	2	(0, 0, 0)	(0.4949, 0.4949, 0)	10.8	0.811611	0.581178			$0.40 \pm 0.05$
22	0	BAM	64	0.2222	2	(0, 0, 0)	(0.1767, 0.1767, 0)	10.8	0.812379	0.610965	0.999534	0.9009	$1.46 \pm 0.02$
	1	ET	80	0.2222	2	(0, 0, 0)	(0.1767, 0.1767, 0)	10.8	0.812001	0.550427			$0.54 \pm 0.05$
23	0	ET	64	0.2222	2	(0, 0, 0)	(-0.1767, 0.1767, 0.5)	10.8	0.793749	0.53149	0.99994	0.881549	$1.88 \pm 0.01$
	1	ET	80	0.2222	2	(0, 0, 0)	(-0.1767, 0.1767, 0.5)	10.8	0.793701	0.468535			$0.28 \pm 0.05$
24	0	ET	64	0.2222	2	(0, 0, 0)	(-0.3535, 0.3535, 0.5)	10.8	0.7935	0.531374	0.999772	0.843376	$2.13 \pm 0.03$
	1	ET	80	0.2222	2	(0, 0, 0)	(-0.3535, 0.3535, 0.5)	10.8	0.79332	0.448148			$0.48 \pm 0.05$
25	0	ET	64	0.2222	2	(0, 0, 0)	(-0.3535, 0.3535, 0.)	10.8	0.812118	0.611108	0.999848	0.895657	$1.78 \pm 0.07$
	1	ET	80	0.2222	2	(0, 0, 0)	(-0.3535, 0.3535, 0.)	10.8	0.811994	0.547343			$0.69 \pm 0.07$

# Results. Reduced NR simulations (II)

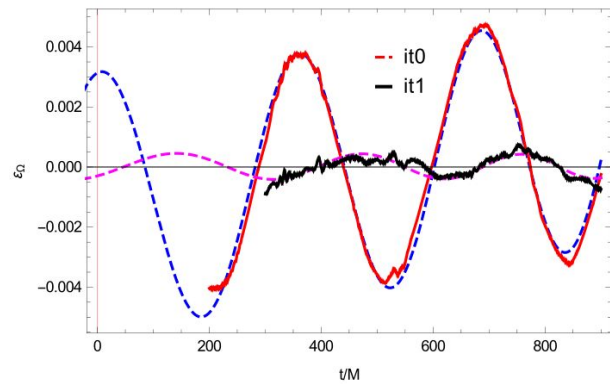
$q1\_ (0, 0, 0) \_ (0, 0, 0) \_ D12$



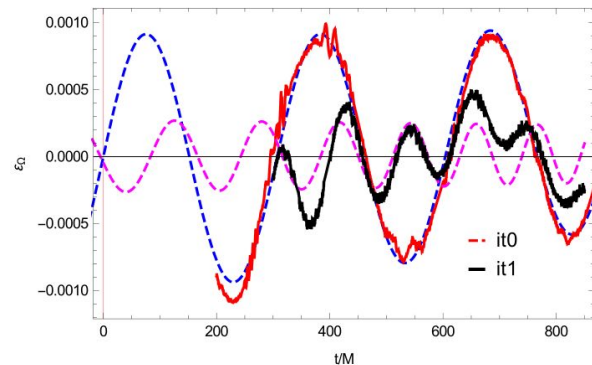
$q2\_ (0, 0, 0.75) \_ (0, 0, 0.75) \_ D11.1117$



$q4\_ (0, 0, -0.8) \_ (0, 0, 0.8) \_ D11$



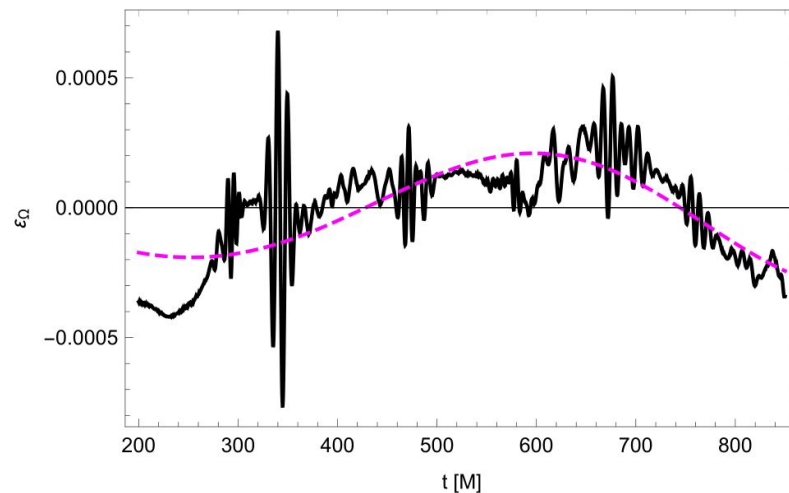
$q2\_ (0, 0, 0) \_ (-0.17, 0.17, 0.5) \_ D10.8$



# Results. NR separation correction (I)

- We test also the separation correction in NR.
- For the configuration ID2,  $q = 1$ ,  $\chi_{1z} = -0.5$ ,  $\chi_{2z} = 0.5$ ,  $D = 11M$

Iteration	Code	N	$\delta r$	$\lambda_r$	$(\varepsilon_\Omega \pm \delta\varepsilon_\Omega) \cdot 10^{-3}$
0	BAM	64			$1.24 \pm 0.03$
1	BAM	64	-0.0023	0.8581	$0.2 \pm 0.2$



# Conclusions

- PN based method to reduce eccentricity from numerical simulations.
- Method tested for two different moving puncture binary black hole evolution codes (ET and BAM).
- Method tested for different mass ratios and spin orientations.
- The method provides eccentricities of  $O(10^{-4})$  in one iteration.
- **Limitations:** short evolutions unable an accurate eccentricity measurement, the higher the initial eccentricity the more iteration will be needed.
- Open questions: could the method work for spectral codes? could the method work for neutron star simulations?